

# High precision time series regression

for Automotive Powertrain Development & More

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#### Introduction: Our use-case

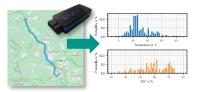
#### From Measurement to Al-based Digital Twins



#### Vehicle



#### Measurement Data



#### Al Model of Powertrain

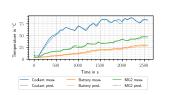


Digital Twin Instance

- Investigate test drives that are not included in the training data
- Investigate control strategies

#### Virtual Test Drive

- Route
- Speed Profile
- Traffic Situation
- Weather





Digital Twin Instance

Analysis

#### Introduction: Our use-case

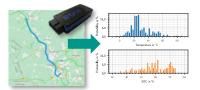
#### From Measurement to Al-based Digital Twins



#### Vehicle



#### Measurement Data











Digital Twin Instance

- What are the challenges?
- What are the special issues in the powertrain?

- highly automated process@FKFS
- training duration ~16h
- 14x RTX3080/3090 @ FKFS
- cloud services possible

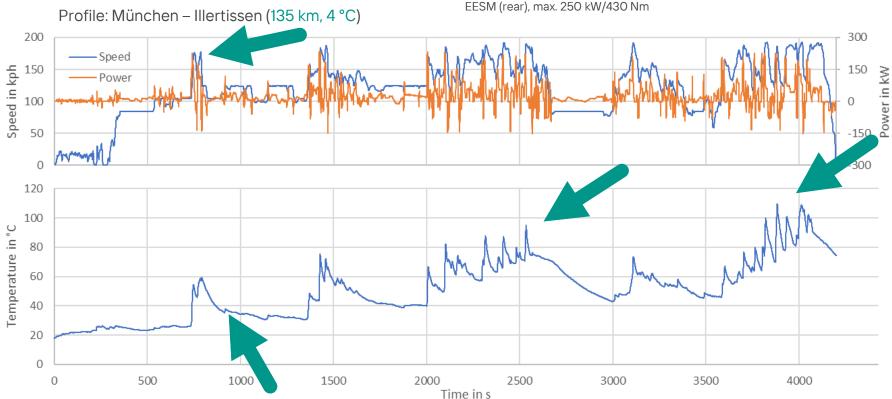
### Example

#### E-Motor: Temperature of stator





BMW i4 eDrive 40 (G26) EESM (rear), max. 250 kW/430 Nm



#### Example





E-Motor: Temperature of stator

BMW i4 eDrive 40 (G26) 30 Nm Typical task: 300 Al-based temperatur model  $T = f(T_Start, t, v(t), P(t), ...)$ ... time series regression Challenges -300 Time dependencies are crucial High precision is crucial Inertias (mechanical, thermal, chemical, fluid) with different time scales are characteristic of the powertrain ZU 500 1000 1500 2000 2500 3000 3500 4000 Time in s

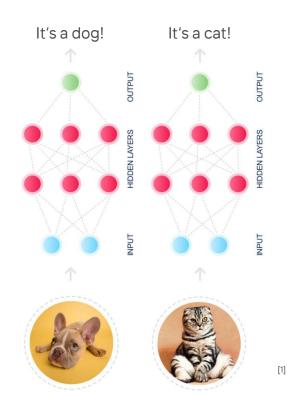
### Introduction: Typical Neuronal Networks

#### Example: Image Recognition



Layer #2:

Layer #1:

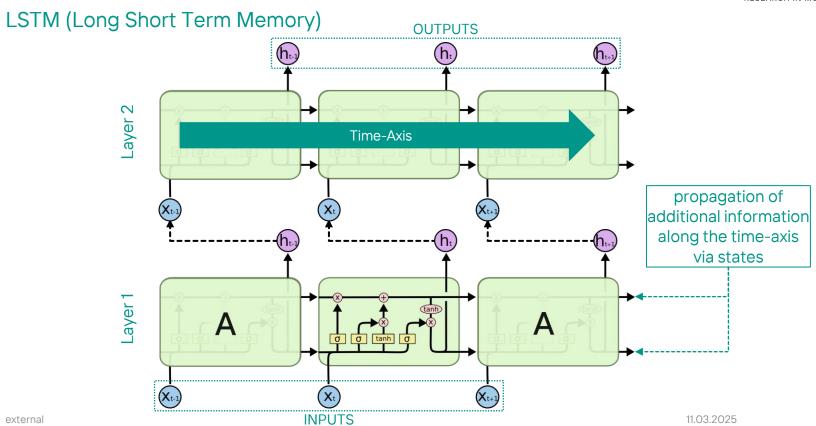


CNN and dense NN are stateless:

the prior experience has no influence on the outcome

### Time-Series Regression





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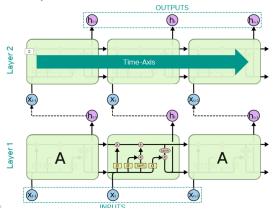
#### **Time-Series Regression**





#### Strenghts:

- Memory of previous timesteps via states
  - long- and short term memory
- Ability to forget irrelevant information
- Very high simulation speed > 100x RT



#### Challenges:

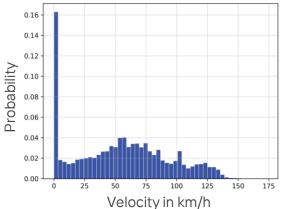
- Initialization of states is non-trivial
- Error accumulation over time
- Good training strategies necessary

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#### **Demonstrator Project**

#### Ford Galaxy FHEV

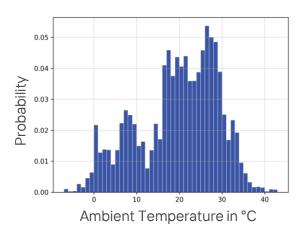
- Test vehicle is rented and unmodified
- Data-logging via OBD2-port
- Only openly available control unit signals are utilised (no OEM support)
- 160 cycles covering over 7400 km







Source: https://www.ford.de/fahrzeuge/ford-galaxy



#### Results

## FKFS RESEARCH IN MOTION.

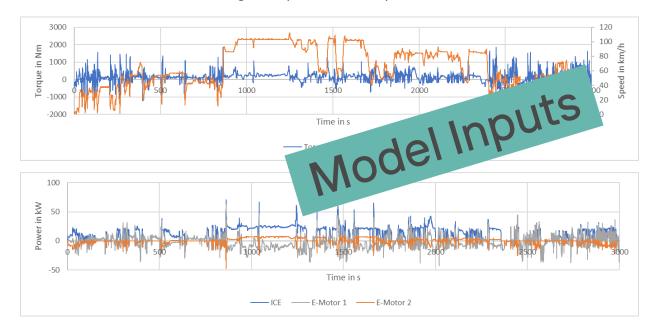
#### Temperature Model of Battery and E-Motor

#### Ford Galaxy Hybrid:

- 1x ICE, 2x E-Motor
- 7400 km of real world driving
- Random data split:
  20% test, 30% validation,
  50% training



Profile: Montecchio – San Gimignano (108 km, 27 °C)

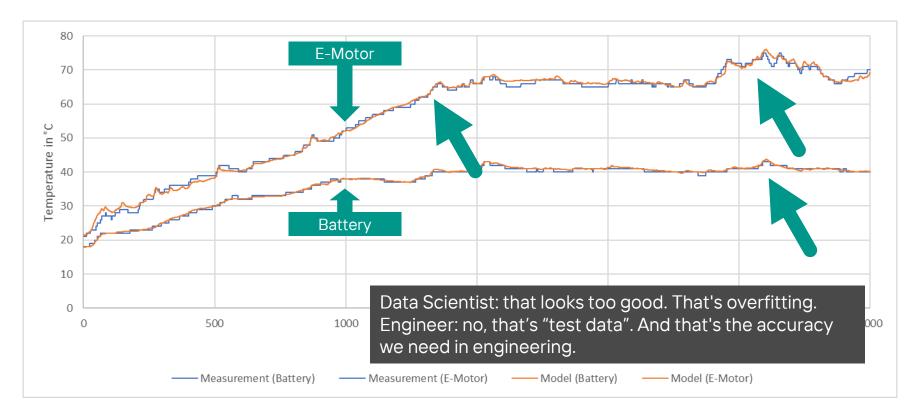


#### Results: Ford Galaxy Hybrid

#### Temperature Model







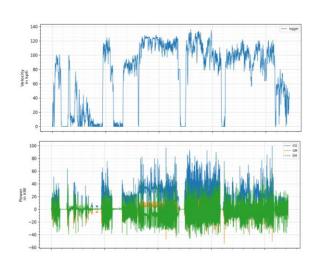
#### Results: Ford Galaxy Hybrid

#### Temperature Model

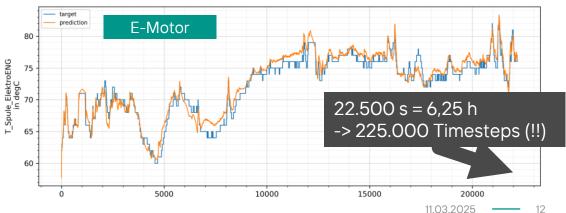




Bissone (I) -> Montecchio (I)





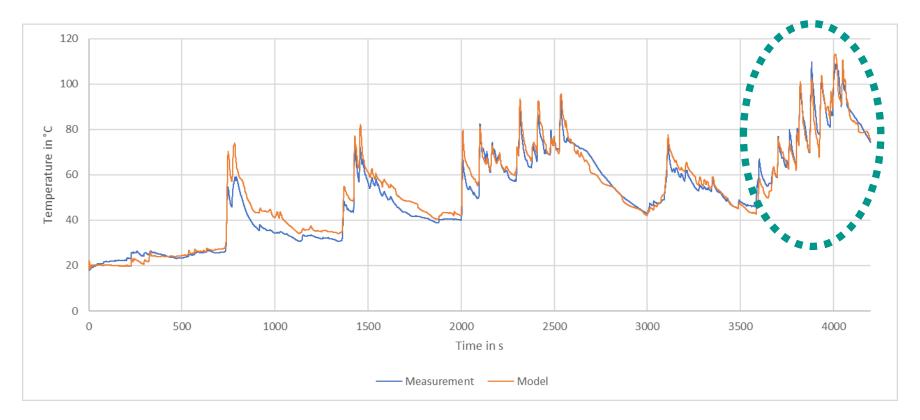


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#### Results: BMW i4 eDrive 40



#### Temperature Model (E-Motor)

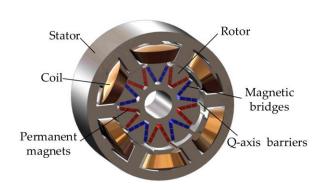


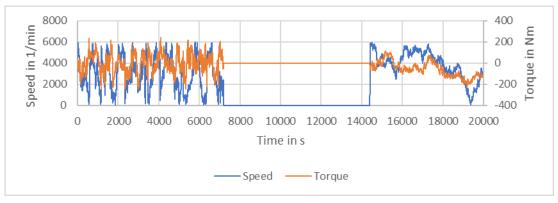
#### Results: Training on dynamic test bench data

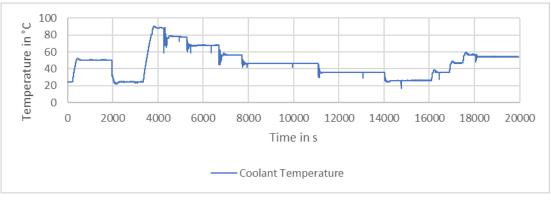
## RESEARCH IN MOTION.

#### Overview

- Permanent Magnet Synchronous Motor (PMSM)
- max. 32 kW
- matches with the prototype of a German OFM



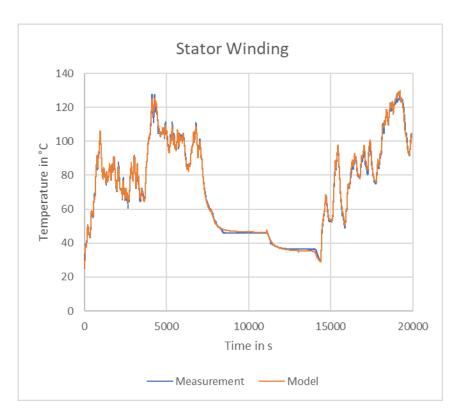


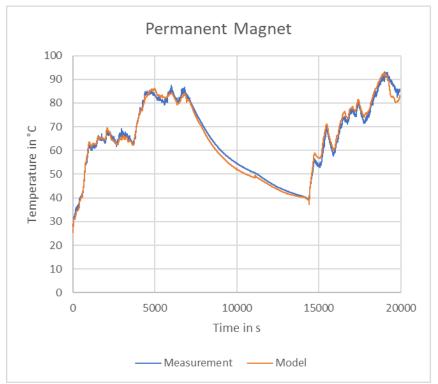


### Results: Training on dynamic test bench data



#### **Temperature Model**





#### Conclusion



#### Digital twins based on measurement data & Al

- Very high accuracy is achievable
- Models can be trained in ~16 hours (high degree of automation)
- Very high simulation speed 100 10.000x faster than real-time
- Expert knowledge on the network architecture of recurrent neural networks and on the handling of their internal memory states necessary
- Expert knowledge of the domain is crucial: very few model inputs to enable "learning" of the physics.

#### Other Use-Case: fleet measurements

New approach to analyse real word driving data



High prediction quality of the Digital Twin is crucial for this application

Vehicle

Measurement Data

Al model of vehicle

Virtual test drive











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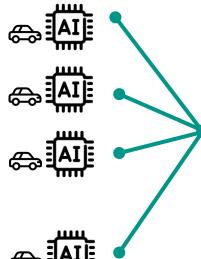


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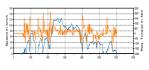




Digital twin instances

exactly same ...

- route
- speed profile
- traffic situation
- weather





Digital twin instances

Difference between digital twins

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### Other Use-Case: Analysis of aging effects

Based on real world driving data



Monitoring the scope of validity of the Al models is crucial!



0 ...

30.000 km

60.000 ...

90.000 km

#### Measurement Data

Al model of vehicle

#### Virtual test drive

#### exactly same ...

- route
- speed profile
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- weather









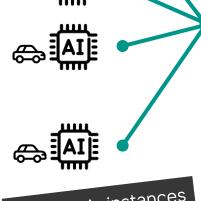




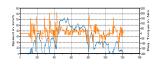














Digital twin instances

can Aging

#### Other use-case: Motorsports



Motorsports: Racing strategy and laptime optimization based on Digital Twins

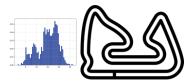
Vehicle

Measurement Data

Al model of vehicle

Virtual test drive









10.000x faster than RT

Digital twin Digital twin

FKFS is proud to be AI partner of GM motorsports

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# Thank you for your attention.

Dr.-Ing.

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